



TBC-HXS52 series multi-range current sensor is a closed loop device based on the principle of the hall effect, with a galvanic isolation between primary and secondary circuit, it provides accurate electronic measurement of DC, AC or pulsed currents.

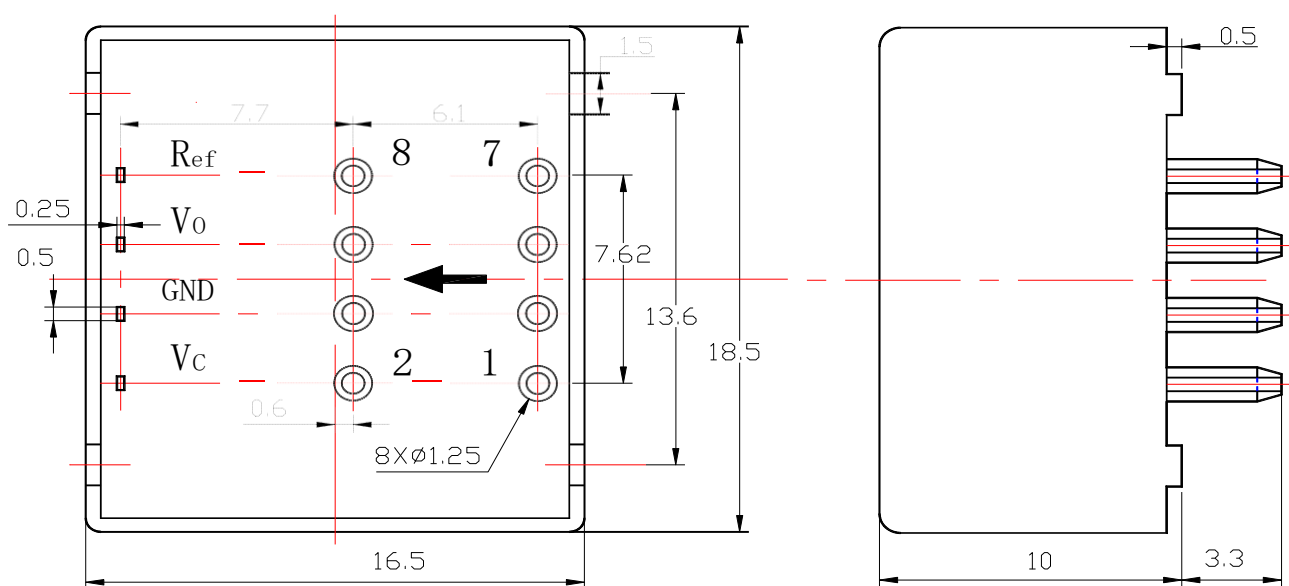
Electrical data(Ta=25°C±5°C)

| <div>Type</div> <div>Parameter</div> | TBC10HXS52 | TBC20HXS52 | TBC30HXS52 | TBC50HXS52 | Unit |
|--------------------------------------|------------------|------------|------------|------------|-------|
| Rated input (Ipn) | ±10 | ±20 | ±30 | ±50 | A |
| Measuring range (Ip) | ±11 | ±22 | ±33 | ±55 | A |
| Secondary Turns (Ns) | 1000 | 1000±2 | 1200±1 | 1000±1 | T |
| Internal measuring resister | 50±0.1% | 25±0.1% | 20±0.1% | 10±0.1% | Ω |
| Rated output voltage | 2.0±0.5% | 2.0±0.5% | 2.0±0.5% | 2.0±0.5% | V |
| Supply voltage | +5±5% | | | | V |
| Power consumption | 15+Ip/Ns | | | | mA |
| Reference voltage | +2.5±0.4% | | | | V |
| Zero voltage | @ Ip=0 | +2.5±0.4% | | | V |
| Offset voltage drift | ≤±0.2 | | | | mV/°C |
| Output drift | ≤±0.2 | | | | mV/°C |
| Linearity | @ Ip=0-±Ipn | ≤0.1 | | | %FS |
| Magnetic offset voltage | @Ip=3XIpn-0 | ≤±0.25 | | | %Ipn |
| di/dt accurately followed | > 50 | | | | A/μS |
| Response time | @100A/μS,10%-90% | ≤500 | | | nS |
| Band- width | @-3dB | DC-200 | | | KHz |
| Galvanic isolation | @ 50/60HZ,1min | 3.5 | | | KV |

Applications

- Variable speed drives
- Welding machine
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Electrochemical

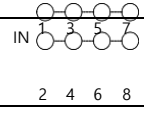
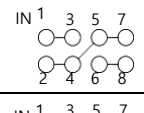
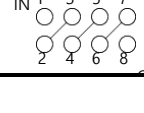
Mechanical dimension (for reference only)



Remarks :

1. All dimensions are in mm.
2. General tolerance $\pm 1\text{mm}$

Pin connections

| Item | Turns | IPN (A) Primary rated current | Vout (V) Rated putout | [mΩ] Primary impedance | [uH] Primary Inductance | Connect point |
|--------------|-------|-------------------------------------|-------------------------|------------------------|-------------------------|---|
| Single Phase | 1 | $\pm 6.0(\pm 20, \pm 30, \pm 50)$ | $2.5 \pm 2.0 \pm 0.5\%$ | 0.05 | 0.025 |  |
| | 2 | $\pm 3(\pm 10, \pm 15, \pm 25)$ | $2.5 \pm 2.0 \pm 0.5\%$ | 0.20 | 0.1 |  |
| | 3 | $\pm 1.5(\pm 5, \pm 7.5, \pm 12.5)$ | $2.5 \pm 2.0 \pm 0.5\%$ | 1.00 | 0.4 |  |

Directions for use

1. When the current will be measured goes through a sensor, the voltage will be measured at the output end. (Note: The false wiring may result in the damage of the sensor).
2. Custom design in the different rated input current and the output voltage available.

Standards

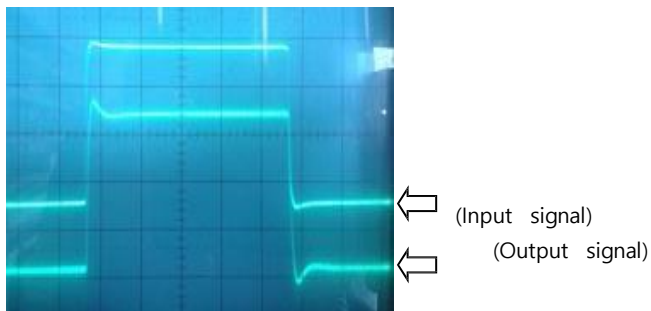
UL94-V0.
EN60947-1:2004
IEC60950-1:2001
EN50178:1998
SJ 20790-2000

General data

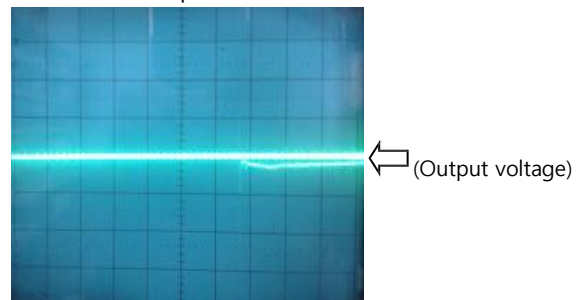
| | Value | Unit | Symbol |
|-----------------------|-------------|------|--------|
| Operating temperature | -40 to +105 | °C | TA |
| Storage temperature | -40 to +125 | °C | TS |
| Mass(approx) | 7 | g | M |

Characteristics chart

Pulse current signal response characteristic



Effects of impulse noise



Input current-output voltage characteristic

Primary Current (I_p)--Output

